

# Game Theory

Department of Electronics

EL-766

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Lecture 13 (Game Theory)

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# Learning in games

- Why learning?
  - For introspection, the rules of the game, rationality of the players, payoff functions – all common knowledge
  - Another problem: for multiple equilibria, how players come to expect the same equilibrium?
- Applicability
- Repeated games
- Teach opponent to play a best response to a particular action, by repeating it over and over again

## Example of sophisticated learning

- How would you play this game, if you were player 1?

	L	R
U	1,0	3,2
D	2,1	4,0

# Sophisticated learning?

- Most learning theory  $\rightarrow$  models for which the incentive is small to alter the future play of the opponents.
  - Examples:
    - large anonymous population: population size large compared to the discount factor
    - Players locked in their choices and discount factor small compared to maximum speed at which the system can possibly adjust

# Common models for learning

- **Fictitious play**

- Players observe only their own matches and play a best response to the historical frequency of play

- **Partial best-response**

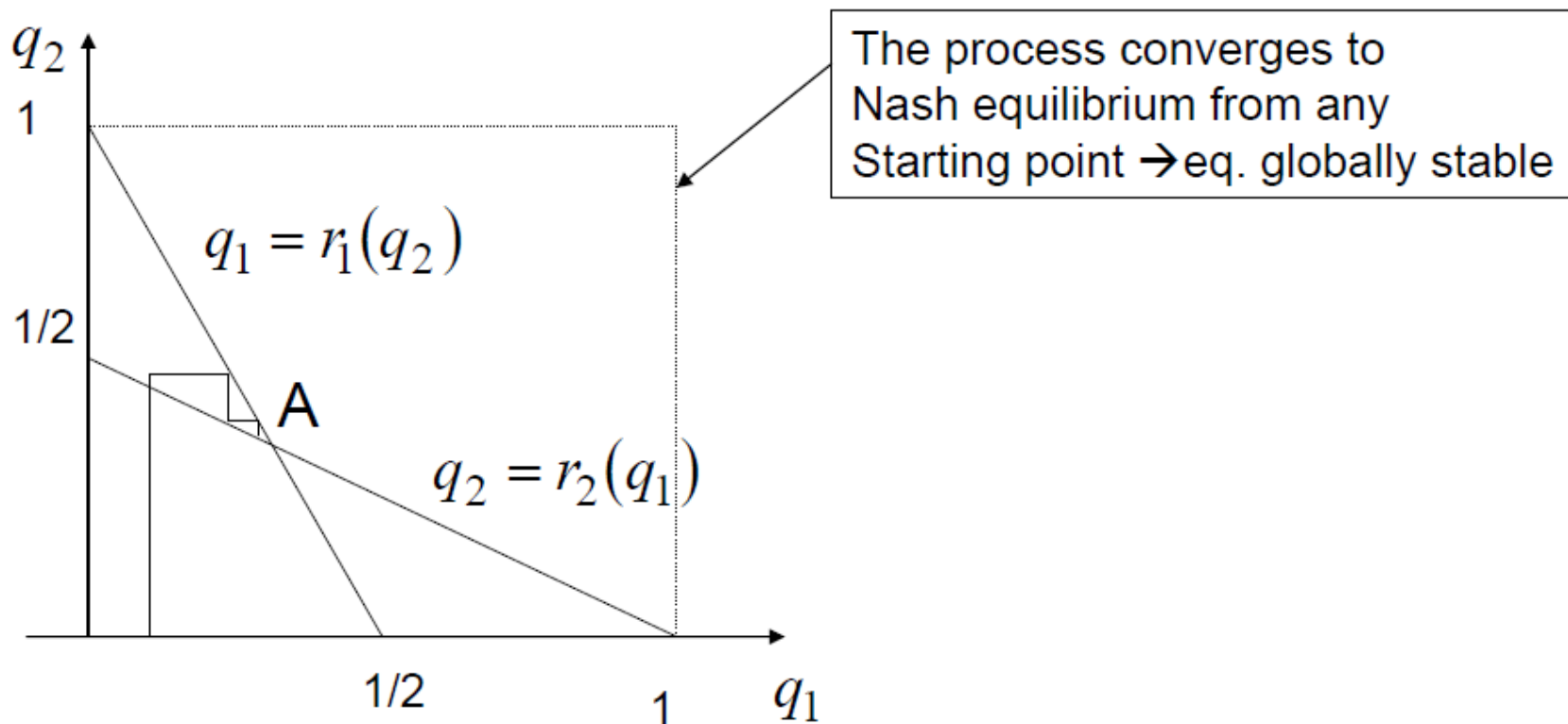
- A fixed portion of users switches each period from its current action to a BR to the aggregate statistics from the previous period

- **Replicator Dynamics**

- The fraction of the population using a given strategy, grows proportionally to that strategy's current payoff.

# One type of learning: Cournot adjustment

- Unique Nash eq. is at the intersection of the reaction curves



# Fictitious play

- Repeated game
- Stationary assumption
- Each player: belief of opponents “strategy” by looking at what happened
- Player then plays best response (BR) according to his belief
- Belief: a prediction of the opponent action distribution, i.e. the degree to which player  $i$  believes player  $j$  will play a certain action.
- Players choose their actions in each period, s.t. to maximize their expected payoff, with respect to their belief for the current period.

# Updating beliefs

- Player  $i$ : initial weight function

$$K_0^i : S^{-i} \rightarrow \mathcal{R}^+$$

- Game iteratively repeated  $\rightarrow$   $K$  updated:

$$K_t(s^{-i}) = K_{t-1}(s^{-i}) + \begin{cases} 1, & \text{if } s_{t-1}^{-i} = s^{-i} \\ 0, & \text{ow.} \end{cases}$$

- Given the frequency vector  $K \rightarrow$  updates beliefs
  - The belief player  $i$  has at time  $t$  about its opponent to play  $s^{-i}$  at time  $t$ :

$$\gamma_t^i(s^{-i}) = \frac{K_t^i(s^{-i})}{\sum_{\hat{s} \in S^{-i}} K_t^i(\hat{s}^{-i})} \longleftarrow \text{Simple normalization}$$